Monte Carlo Methods for 2D Flow Visualization Supplemental Material

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1. Results

We test both our approaches on slices of different vector fields. The BENZENE data set contains the three-dimensional electrostatic field around a benzene molecule. The BORRO and TREFOIL data set are three-dimensional simulations of magnetic fields in different ring and knot configurations [CB11]. Lastly, the CYLINDER data set contains a von-Kármán vortex street in a flow with Reynolds number 160 around a cylinder [Pop04,GGT17]. Fig. 1 compares evenlyspaced streamlines [JL97], line integral convolution [CL93], and our two proposed approaches on all four data sets. A high density of evenly-spaced streamlines may result in many suddenly ending lines. To provide a fairer comparison, we added a tapering to the streamlines (first column in Fig. 1), which was done in three steps. First, evenly-spaced streamlines were computed with the classic algorithm of Jobard and Lefer [JL97], during which the seed points were stored. Second, the lines were discarded and replaced with full streamlines computed from the seed points, resulting in lines that end when they reach a critical point or exit the domain. And third, all lines were rendered with super-sampling in random order, giving each line a finite width (black) and a thin halo (white). By starting from the seed points of the evenly-spaced streamlines, it is guaranteed that the domain is sufficiently densely sampled. The line integral convolution (second column) was contrast-enhanced for all test scenes to serve as baseline. Our smooth vector graphics formulation (third column) visually separates larger flow structures well due to the higher contrast and the distinct color gradients. The light transport simulation (fourth column) exhibits a darkening effect where lines end or when the line density decreases due to diverging flow. Unlike all other approaches, it creates a depth impression that makes the scene more haptic. In the following, we measure the performance of the two approaches.

2. Performance Measurements

We measured the computation time for both our approaches on an Intel i9-10980XE CPU (3.0 GHz) with an NVIDIA RTX 1080 GPU. All measurements are taken for an image resolution of 512×512 pixels. The smooth vector graphics approach is implemented on the GPU, while we targeted Mitsuba to the CPU for the light transport simulation. Table 1 lists the parameters of all test scenes, as well as the computation times. The numerical integra-

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This is an open access article under the terms of the Creative Commons Attribution License, which permits use, distribution and reproduction in any medium, provided the original work is properly cited. tion step size of the RK4 integrator is determined automatically by the Courant-Friedrich-Levy condition for a Courant number of C = 0.5, meaning that the integration step is bounded such that the largest possible integration step cannot move further than 0.5 grid cells. Both our approaches take a set of evenly-spaced streamlines [JL97] as input. We report the initial separation distance d_{sep} and the testing distance d_{test} for both approaches, and list the resulting number of streamlines N that are rendered per data set. The fading distance F, as well as the distances d_{sep} and d_{test} are specified relative to the size of a pixel Δ . Let $X \times Y$ be the image resolution, and let (x_{min}, y_{min}) , and (x_{max}, y_{max}) be the corners of the domain bounding box, then the pixel size Δ is:

$$\Delta = \min(\Delta_x, \Delta_y), \quad \Delta_x = \frac{x_{max} - x_{min}}{X - 1}, \quad \Delta_y = \frac{y_{max} - y_{min}}{Y - 1} \quad (1)$$

Thus, $d_{sep} = 10$ corresponds to a separation distance of 10Δ . If not mentioned otherwise, all SVG images are rendered with 100 samples per pixel (spp), and all LTS images are rendered with 1,024 samples per pixel (spp). The smooth vector graphics rendering takes 116-275 seconds for 100 spp, which averages at about 1.2-2.8 seconds per iteration. The time for the light transport simulation remained consistently at about 75 seconds for 1,024 spp, which corresponds to about 73 milliseconds per iteration.

3. Convergence Sequence

Since both our approaches are computed via Monte Carlo integration, each image needs a number of iterations to converge. In the previous section, we have seen that the light transport solver needs orders of magnitude less time per iteration. However, both approaches might converge at different rates. Does the smooth vector graphics renderer perhaps need fewer iterations for a decent image? In Fig. 2, we depict a convergence sequence for both approaches, in which the results of early iterations are depicted. It turns out that the smooth vector graphics renderer indeed converges with much fewer iterations compared to the light transport simulation. With both approaches, useful previews are obtained after a few seconds, which allows for potential parameter adjustment.

4. Post-Processing for Contrast Enhancement

Prior state-of-the-art work on LIC, such as FastLIC [HS98], applies a post-processing to enhance the contrast of LIC visualiza-

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Figure 1: Results of evenly-spaced streamlines [JL97], line integral convolution [CL93], and our two approaches in the four data sets.

tions. In Figs. 3–6, we apply three contrast enhancement methods, which are all implemented in Matlab. The first, called imadjust, scales the data values, such that 1% of the lower and upper range of the values is saturated at low and high intensities, respectively. The second method, named histeq, applies a standard histogram equalization. The third method, called adapthisteq, performs histogram equalization locally in small regions rather than on the full image at once. Table 2 reports quantitative metrics for the difference between the image without contrast enhancement and the

image with contrast enhancement, for all data sets and all four visualization methods.

For the evenly-spaced streamlines, histeq turns out to be counter-productive as it darkens the image, while imadjust and adapthisteq have a negligible effect. This can also be seen in the metrics. While imadjust has no effect at all, adapthisteq has almost no difference, and histeq shows a quantitative difference in all metrics, i.e., in SSIM, RMSE, and PSNR.

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| | | Smooth Vector Graphics (SVG) | | | | | | Light Transport Simulation (LTS) | | | | | | |
|----------|----------------|------------------------------|------------|-------|-----|-----|------------|----------------------------------|------------|--------|----|-------|------------|--|
| Dataset | Figure | d_{sep} | d_{test} | Ν | F | spp | time (sec) | d_{sep} | d_{test} | Ν | F | spp | time (sec) | |
| BENZENE | Fig. 1 | 10 | 1.8 | 3,614 | 50 | 100 | 202.57 | 2 | 0.9 | 12,848 | 20 | 1,024 | 73.31 | |
| BORRO1 | Fig. 1 (paper) | 10 | 1.8 | 1,769 | 50 | 100 | 273.44 | 2 | 0.9 | 8,748 | 40 | 1,024 | 74.45 | |
| BORRO2 | Fig. 1 | 10 | 1.8 | 1,677 | 50 | 100 | 275.80 | 2 | 0.9 | 8,296 | 40 | 1,024 | 73.56 | |
| BORRO3 | Fig. 2 | 10 | 1.8 | 1,818 | 50 | 100 | 273.50 | 2 | 0.9 | 8,702 | 40 | 1,024 | 75.00 | |
| TREFOIL | Fig. 1 | 10 | 2.25 | 1,604 | 50 | 100 | 206.61 | 2 | 0.9 | 9,193 | 40 | 1,024 | 73.40 | |
| Cylinder | Fig. 1 | 40 | 2.7 | 664 | 100 | 100 | 116.25 | 2 | 0.9 | 7,741 | 80 | 1,024 | 74.14 | |

Table 1: Performance measurements and parameters for all test scenes. Input to our approaches is a set of N evenly-spaced streamlines, computed by the method of Jobard and Lefer [JL97], using the separation distance d_{sep} and the testing distance d_{test} . Both distances as well as the fading distance F are measured in pixels. The time (in seconds) is reported for the total number of samples per pixel (spp).



Figure 2: A convergence sequence for both proposed Monte Carlo methods on BORRO3, showing how the noise reduces quickly after few iterations. The top row shows the smooth vector graphics (SVG) approach, and the bottom row shows the light transport simulation (LTS).

Visually, we observe that imadjust was most effective in the LIC visualizations, which is why we applied this method in the LIC images throughout the paper. This is also the approach used in an open source FastLIC implementation [BS05]. From the metrics it can be seen that the post-processing had a significant effect. The adapthisteq enhancement caused a similar amount of change in the BENZENE and the CYLINDER data set for LIC as it did for our smooth vector graphics approach.

For our smooth vector graphics approach the post-processing has a minor effect. Apart from the aforementioned case of adapthisteq being applied to BENZENE and CYLINDER, all metrics (SSIM, RMSE, and PSNR) have been significantly better for the smooth vector graphics approach than for LIC.

With our light transport simulation approach, the histeq is counter-productive as it darkened the image too much. Both imadjust and adapthisteq have again a negligible effect. Quantitatively, the contrast enhancement had less effect on the light transport simulation method than on the smooth vector graphics method. From these experiments, we conclude that post-processing is not strictly necessary with our approaches. As was known from prior work, post-processing is essential for LIC.

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Figure 3: Application of contrast enhancement methods for the post-processing of evenly-spaced streamlines [JL97].

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Figure 4: Application of contrast enhancement methods for the post-processing of line integral convolutions [CL93].



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Figure 5: Application of contrast enhancement methods for the post-processing of our smooth vector graphics approach.

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imadjust





Figure 6: Application of contrast enhancement methods for the post-processing of our light transport simulation approach.

Input

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| | | Evenly-spaced | | | Line integral convolution | | | SVG (ours) | | | LTS (ours) | | |
|----------|-------------|---------------|---------|-----------------------|---------------------------|---------|------------------------|------------|---------------------------|---------------|------------|---------|---------------|
| Data set | Method | SSIM↑ | RMSE↓ | $\text{PSNR}\uparrow$ | SSIM↑ | RMSE↓ | $\text{PSNR} \uparrow$ | SSIM↑ | $\text{RMSE}{\downarrow}$ | PSNR ↑ | SSIM↑ | RMSE↓ | PSNR ↑ |
| Borro2 | imadjust | 1.0000 | 0.0000 | ∞ | 0.4946 | 39.2263 | 16.2593 | 0.9813 | 9.4662 | 28.6073 | 0.9869 | 11.3712 | 27.0147 |
| | histeq | 0.8947 | 41.9222 | 15.6819 | 0.3457 | 60.4029 | 12.5097 | 0.8983 | 24.0656 | 20.5029 | 0.9648 | 16.8957 | 23.5753 |
| | adapthisteq | 0.9969 | 7.4426 | 30.6963 | 0.5435 | 33.0318 | 17.7522 | 0.8936 | 24.8920 | 20.2096 | 0.9613 | 18.8085 | 22.6437 |
| TREFOIL | imadjust | 1.0000 | 0.0000 | ∞ | 0.8406 | 32.2618 | 17.9570 | 0.9812 | 9.7242 | 28.3737 | 0.9921 | 7.7739 | 30.3180 |
| | histeq | 0.9017 | 40.4111 | 16.0008 | 0.6733 | 54.8102 | 13.3536 | 0.9068 | 22.7796 | 20.9799 | 0.9712 | 13.5449 | 25.4953 |
| | adapthisteq | 0.9971 | 7.3935 | 30.7538 | 0.8749 | 29.0006 | 18.8827 | 0.9013 | 24.2755 | 20.4275 | 0.9666 | 17.4583 | 23.2908 |
| Benzene | imadjust | 1.0000 | 0.0000 | ∞ | 0.8402 | 34.8589 | 17.2845 | 0.9675 | 12.9666 | 25.8742 | 0.9860 | 11.6198 | 26.8268 |
| | histeq | 0.8992 | 41.0343 | 15.8679 | 0.6850 | 54.7550 | 13.3623 | 0.8742 | 27.3019 | 19.4070 | 0.9235 | 39.4217 | 16.2161 |
| | adapthisteq | 0.9966 | 8.0024 | 30.0664 | 0.8740 | 30.0843 | 18.5640 | 0.8709 | 28.0216 | 19.1810 | 0.9444 | 30.5869 | 18.4201 |
| Cylinder | imadjust | 1.0000 | 0.0000 | ∞ | 0.8142 | 34.6593 | 17.3344 | 0.9719 | 11.0461 | 27.2667 | 0.9787 | 14.8935 | 24.6708 |
| | histeq | 0.9079 | 38.8724 | 16.3380 | 0.6380 | 56.8151 | 13.0415 | 0.8853 | 24.6589 | 20.2913 | 0.9181 | 38.9723 | 16.3157 |
| | adapthisteq | 0.9967 | 7.7819 | 30.3091 | 0.8725 | 27.0444 | 19.4892 | 0.8705 | 26.3995 | 19.6989 | 0.9313 | 32.1677 | 17.9824 |

Table 2: This table reports the differences between visualizations with and without contrast enhancement, here listed for all data sets and for three different contrast enhancement methods. For comparison, SSIM (higher is better), RMSE (lower is better), and PSNR (higher is better) are reported. PSNR is measured in dB.